

# Estimation of Nonlinear Trends Using High-frequency Water-quality Monitoring Data

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# Motivation

- ❖ Increasing collection of high-frequency water data
- ❖ A common question: is water quality improving over time
- ❖ Traditional trend estimation method
- ❖ Trend estimation method for high frequency data

# Motivation

- ❖ Start with seasonal-trend decomposition procedure
  - Seasonal, trend and the remainder components
  - Atmospheric CO<sub>2</sub> concentration and temperature
- ❖ Need a universal approach to model different constituents
  - Ranging from water temperature to turbidity
- ❖ Generalized Additive Models (GAMs)

# Study Area

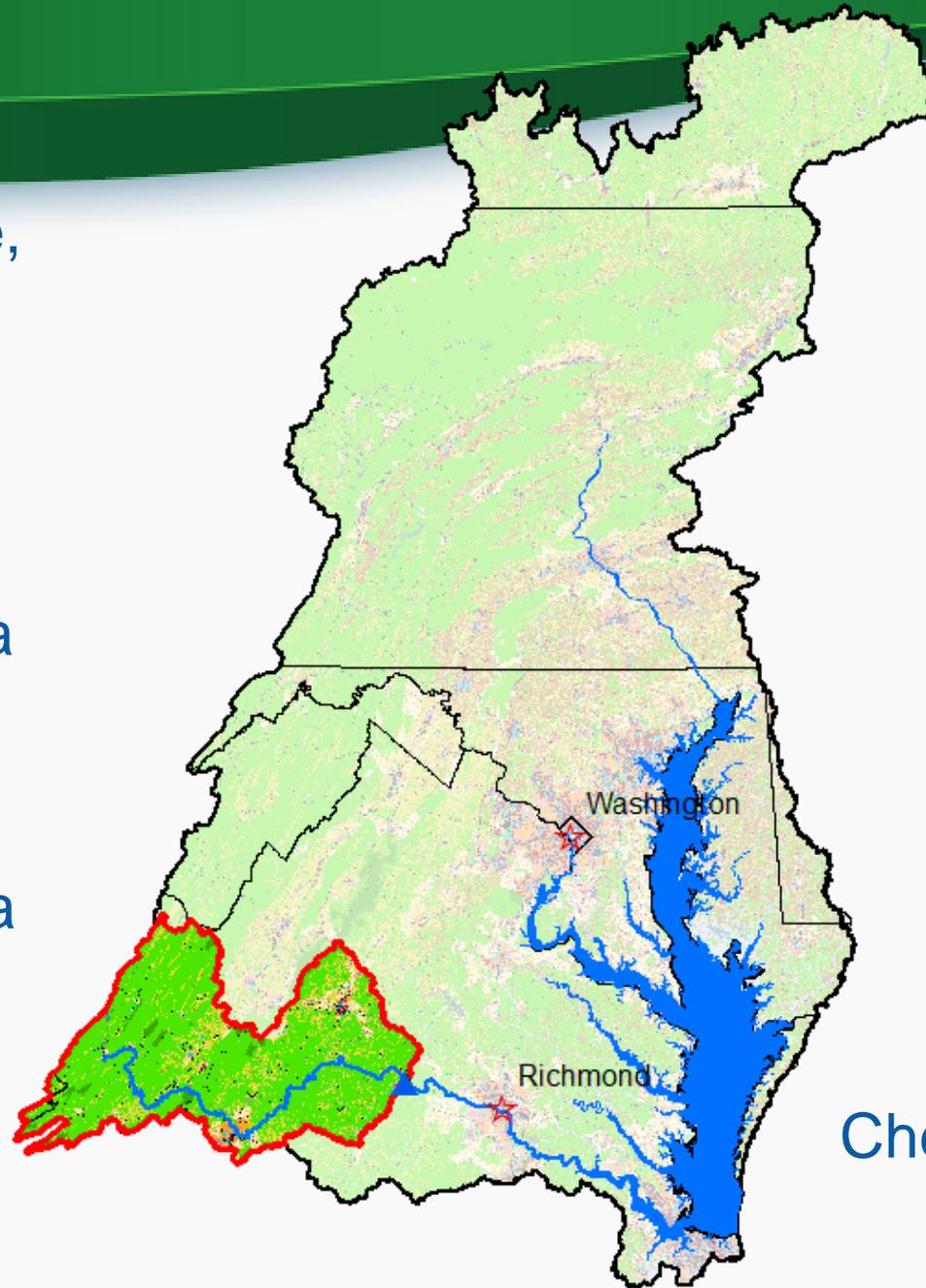
James River at Cartersville,  
VA (02035000)

Area: 16,190 km<sup>2</sup>

The longest river in Virginia

15-min high frequency data

Mean daily value for trend  
estimation



2012 land use map

Urban: 7.5%

Ag: 16%

Forest: 73%

Chesapeake Bay

# Generalized Additive Model (GAM)

Generalized: many response distributions other than normal

Additive: terms add together

$$g(E(y_i)) = \beta_0 + f_1(x_{1i}) + f_2(x_{2i}) + \dots + \varepsilon_i \quad (1)$$

$g$  is a link function

$y_i \sim$  some exponential family distribution

$f_1, f_2 \dots$  are unknown smooth functions

$x_1, x_2 \dots$  are covariates

$\varepsilon_i$  can have random effects

# GAM Theory - Smooth Function

Smooth function (spline): sum of basis functions  $b$

and their corresponding regression coefficients  $\beta$

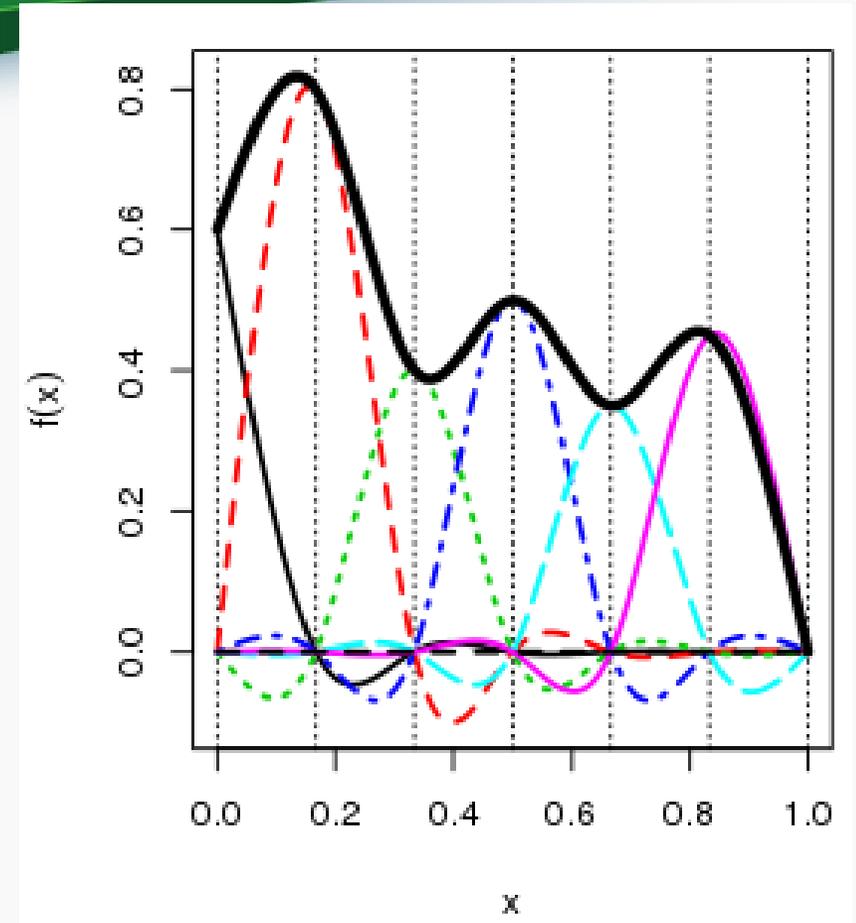
$$f(x) = \sum_{j=1}^k b_j(x)\beta_j$$

$k$ : number of knots - basis dimensions used for the spline

The model (1) can be written in a linear way:

$$g(E(y)) = X\beta + \varepsilon \quad (2)$$

GAM - a generalized linear model (GLM) with linear predictor involving a sum of smooth functions of covariates, subject to smoothing penalties



# GAM Theory – Correlation in Data

- ❖ GAMs assume that residuals are identically and independently distributed (i.i.d.)

This assumption is too strong for daily time series

- ❖ Time-series data: sequential time points will be highly correlated
- ❖ Include autoregressive moving average (ARMA) model for errors in GAM model
- ❖ Generalized Additive Mixed Model (GAMM): to handle residual correlation

$$g(E(y)) = X\beta + \varepsilon \quad (2)$$

$$g(E(y)) = X\beta + A + \varepsilon \quad (3)$$

# Water Temperature GAM Model

Water Temperature ~ s(season) + s(time)

Formula:

```
WT ~ s(nDay, bs = "cc", k = 20) + s(Time, bs = "cr", k = 20)
```

Parametric coefficients:

	Estimate	Std. Error	t value	Pr(> t )
(Intercept)	16.2111	0.1055	153.7	<2e-16 ***

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signif. codes: 0 '\*\*\*' 0.001 '\*\*' 0.01 '\*' 0.05 '.' 0.1 ' ' 1

Approximate significance of smooth terms:

	edf	Ref.df	F	p-value
s(nDay)	13.169	18.000	367.694	< 2e-16 ***
s(Time)	7.378	7.378	3.871	0.00025 ***

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signif. codes: 0 '\*\*\*' 0.001 '\*\*' 0.01 '\*' 0.05 '.' 0.1 ' ' 1

R-sq.(adj) = 0.94

Scale est. = 5.1415      n = 4401

s(nDay) is the smoothing function of seasonal covariate.

s(time) is the smoothing function of time covariate.

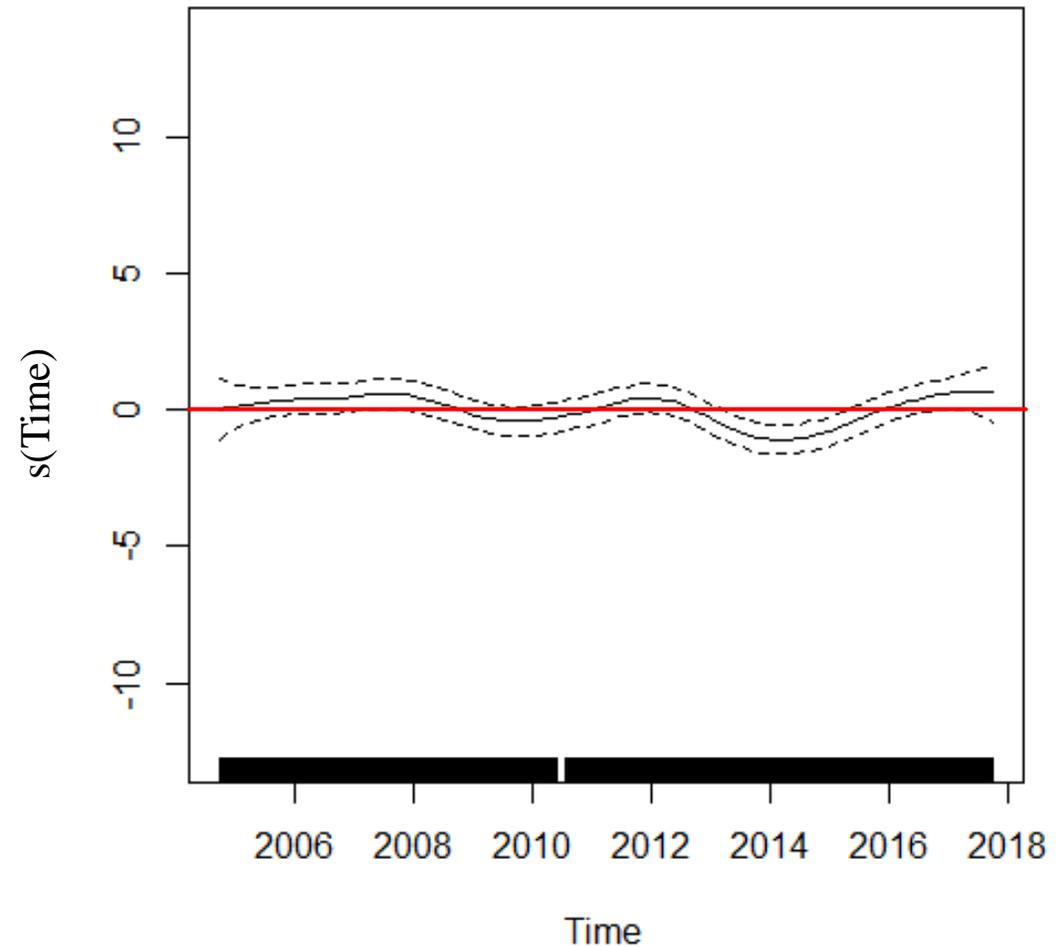
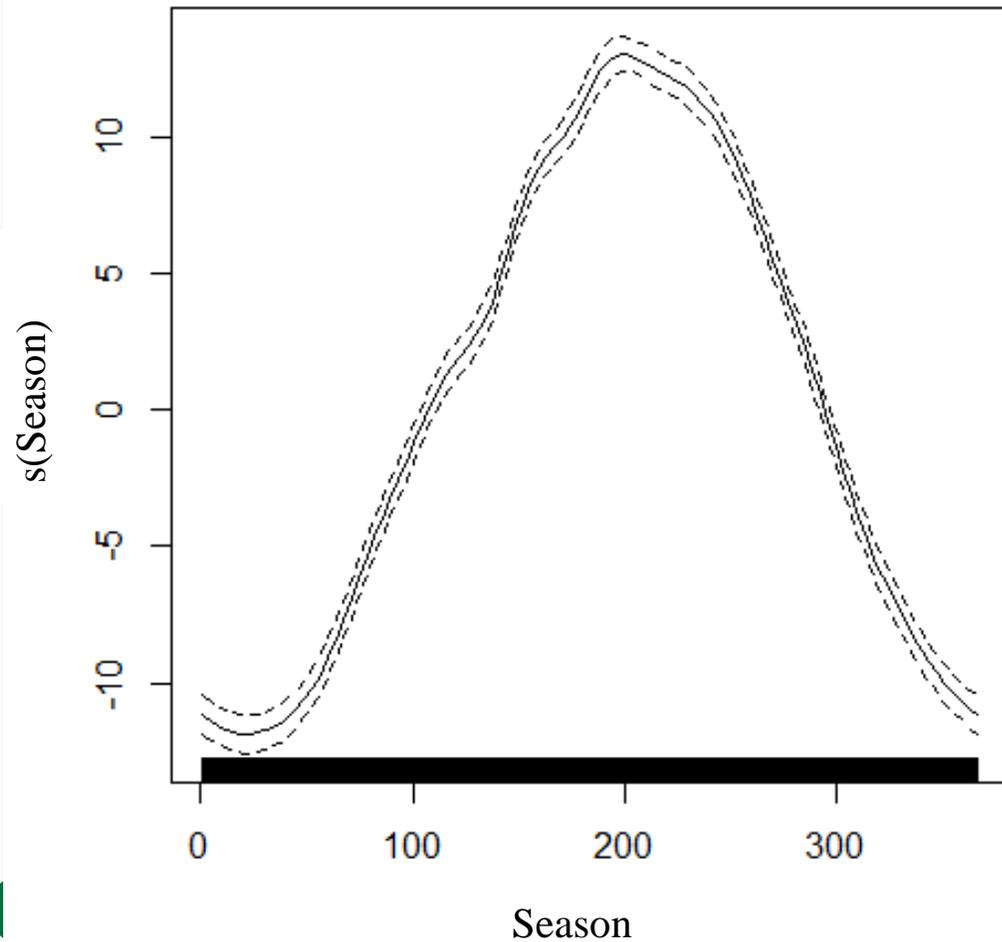
"cr": cubic spline basis

"cc": cyclic cubic spline

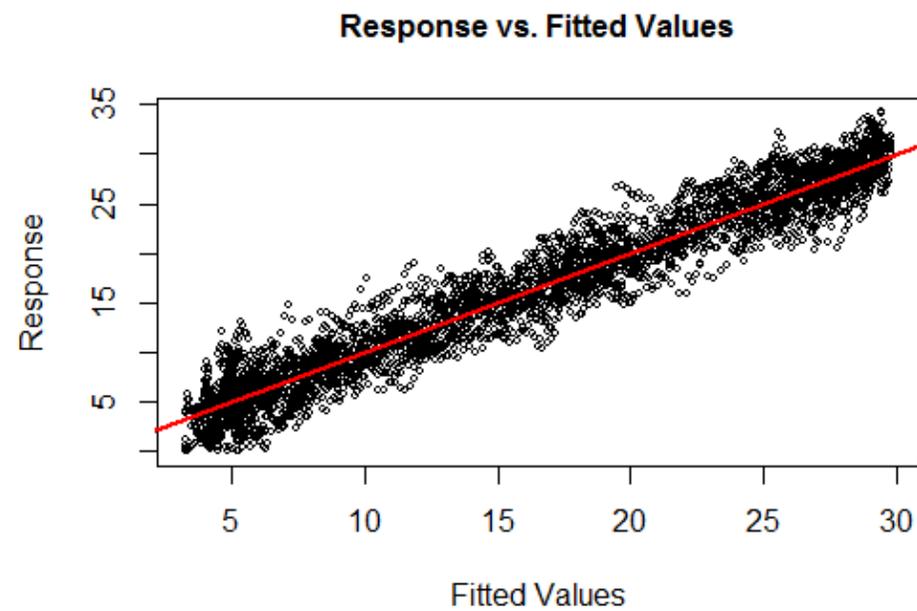
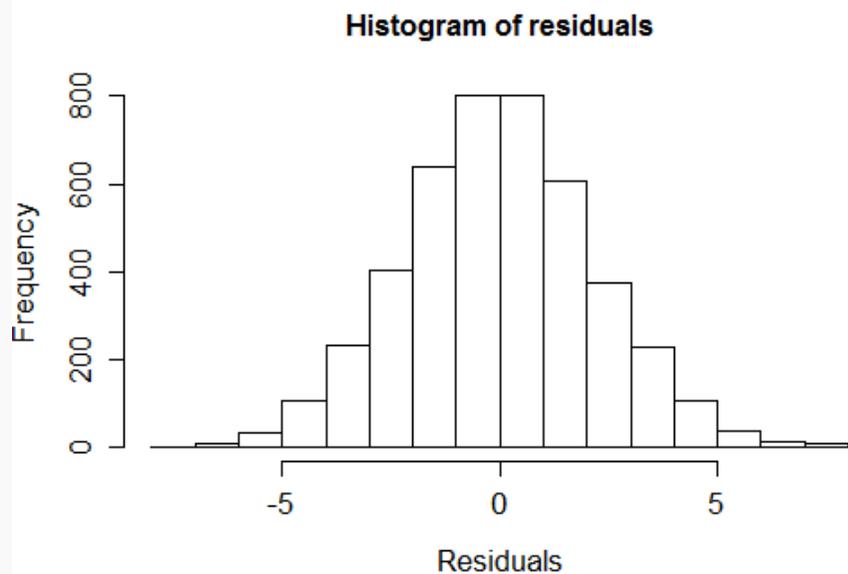
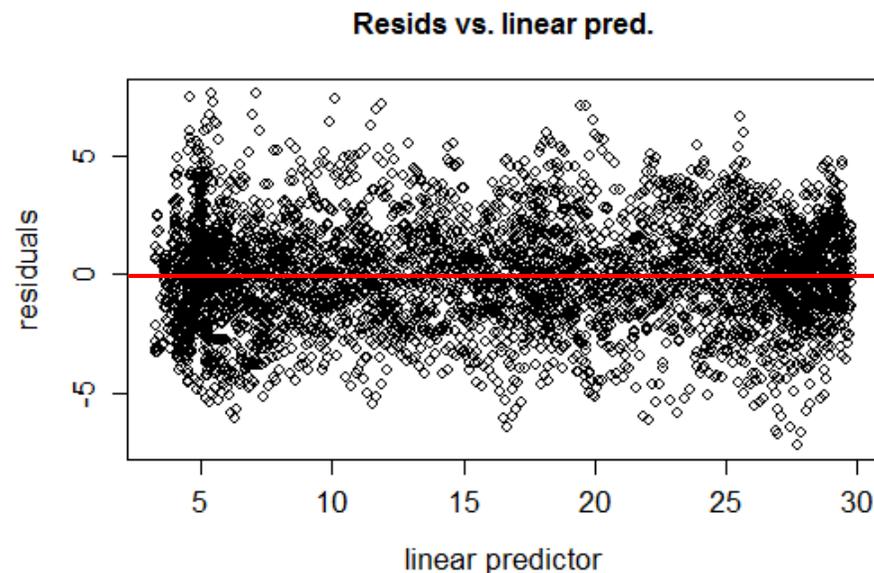
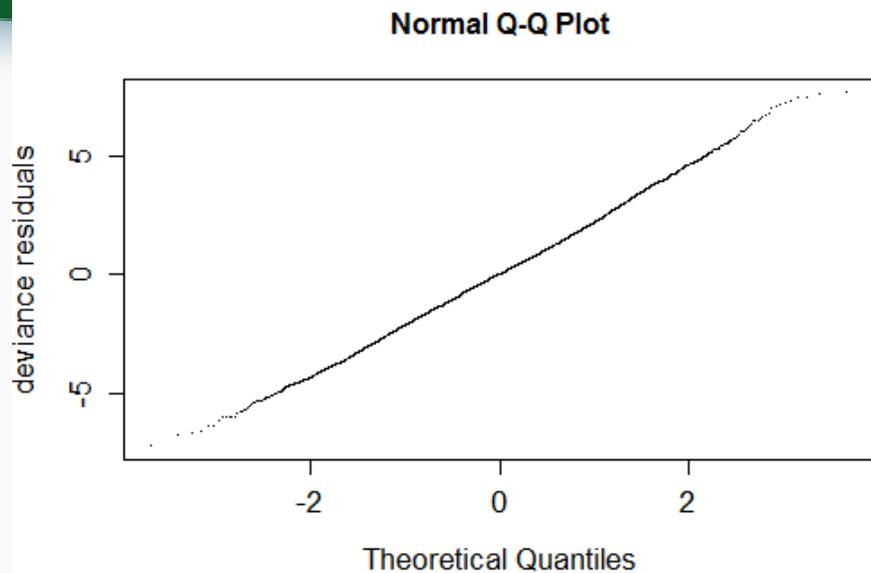
Adj-R<sup>2</sup>

# Water Temperature GAM Model

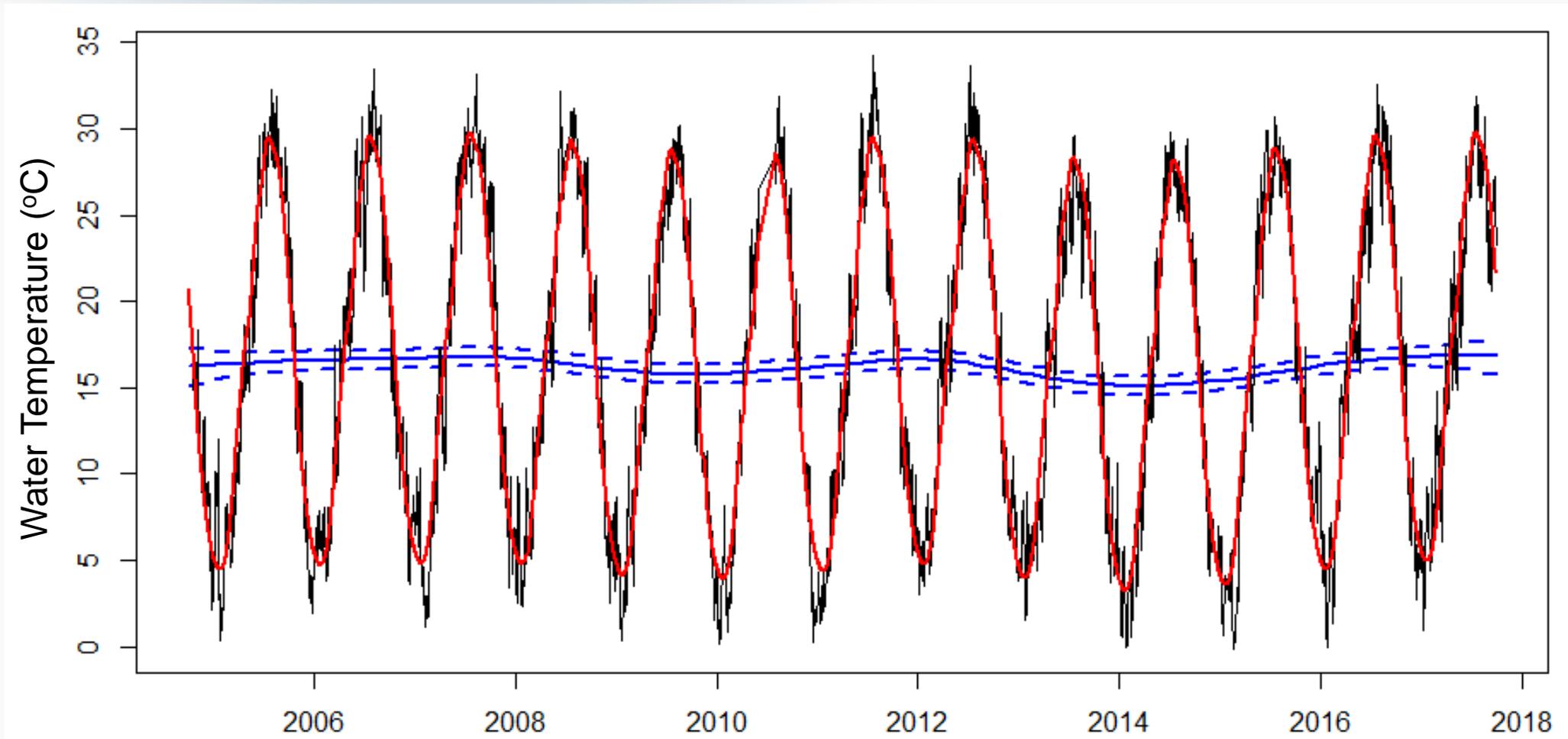
- ❑ Water Temperature  $\sim$  s(season) + s(time)
- ❑ The effect of each smooth function on water temperature



# Water Temperature GAM Model



# Water Temperature – Time Series



— Obs

— Sim

— s(Time)

Mean = 16.21 °C

# Water Temperature – Time Series

2012-01-01 / 2013-12-30

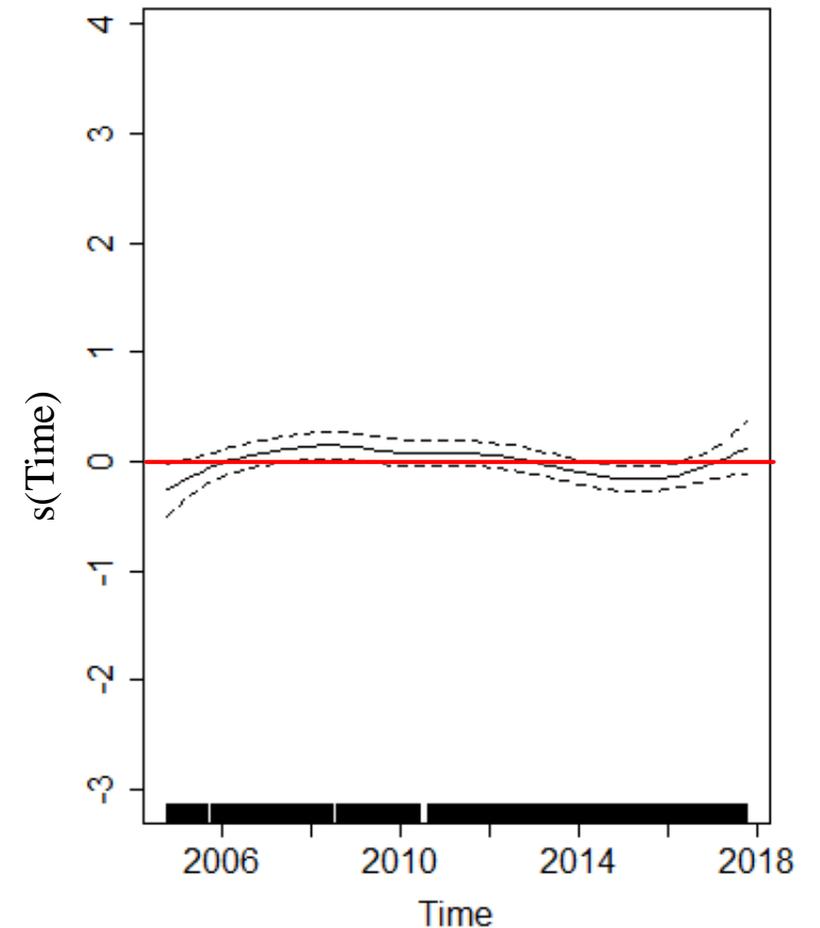
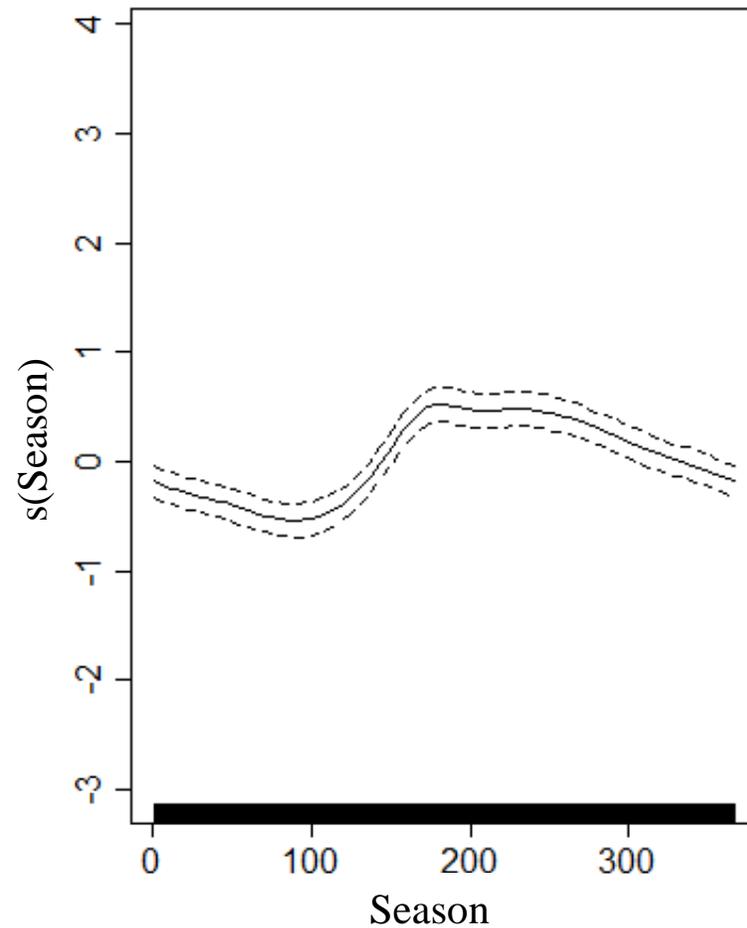
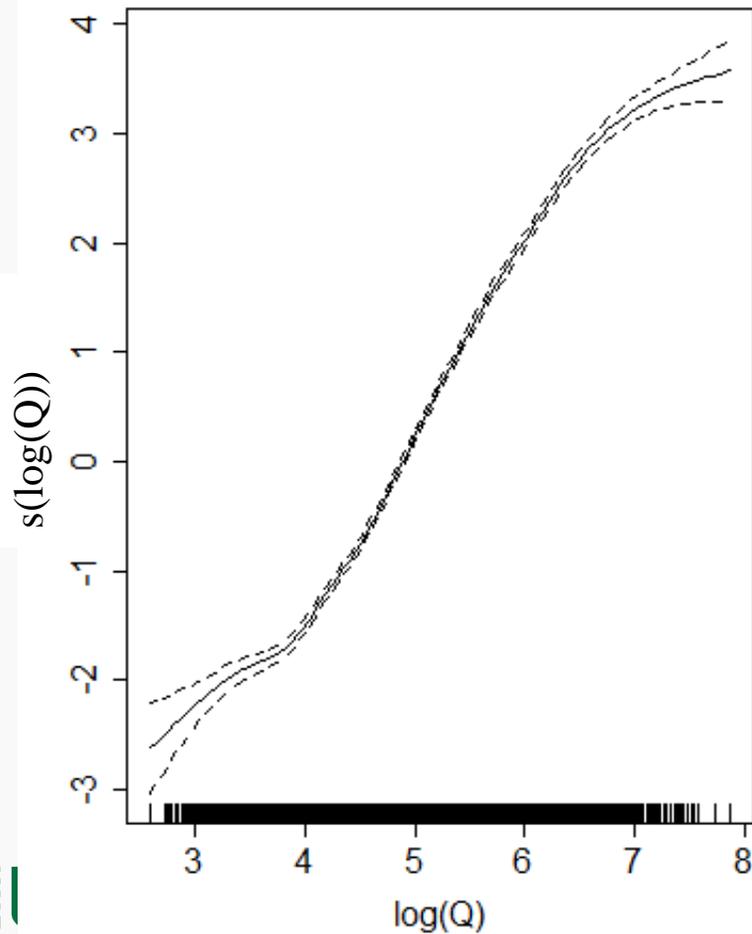


Jan 01 2012    Jun 01 2012    Nov 01 2012    Apr 01 2013    Sep 01 2013

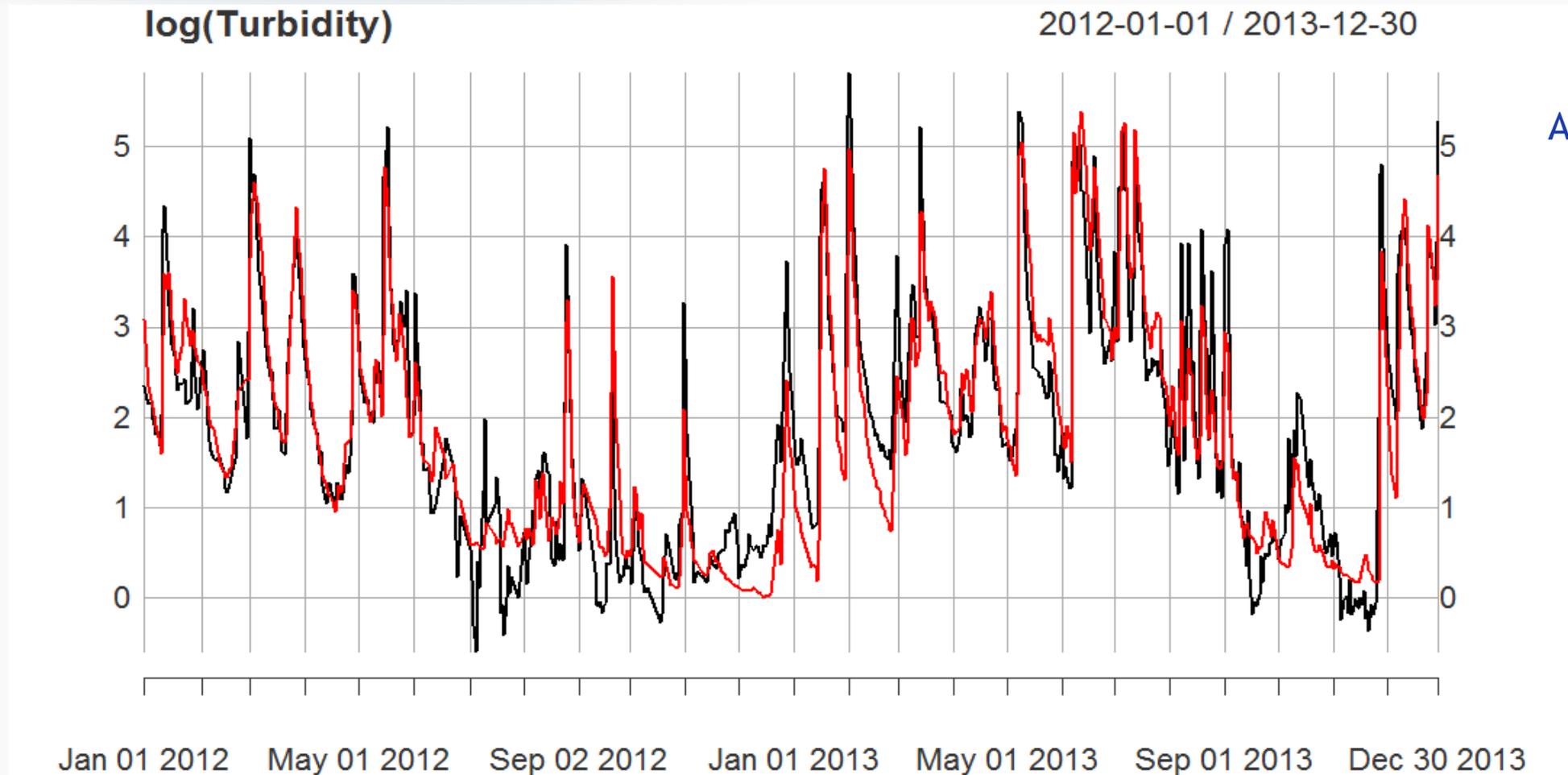
— Obs    — Sim

# Turbidity GAM Model

- $\text{Log}(\text{Turbidity}) \sim s(\log(Q)) + s(\text{season}) + s(\text{time})$
- The effect of each smooth function on turbidity



# Log-Turbidity - Simulation vs. Observation



Adj-R<sup>2</sup> = 0.79

# Trend & CI Estimation Between Two End-points

- ❖ GAM model has an underlying parametric representation

$$\hat{\eta}_p = f(\text{time}) = X_p \hat{\beta}$$

$\hat{\eta}_p$ : smooth function of time component

$X_p, \beta$  are model matrix and coefficient vector

- ❖ Derive the *mean* of the difference between the two endpoints (*trend*) and the standard error of this difference
- ❖ Conduct statistical inference using standard statistical theory
- ❖ Confidence interval and p-value

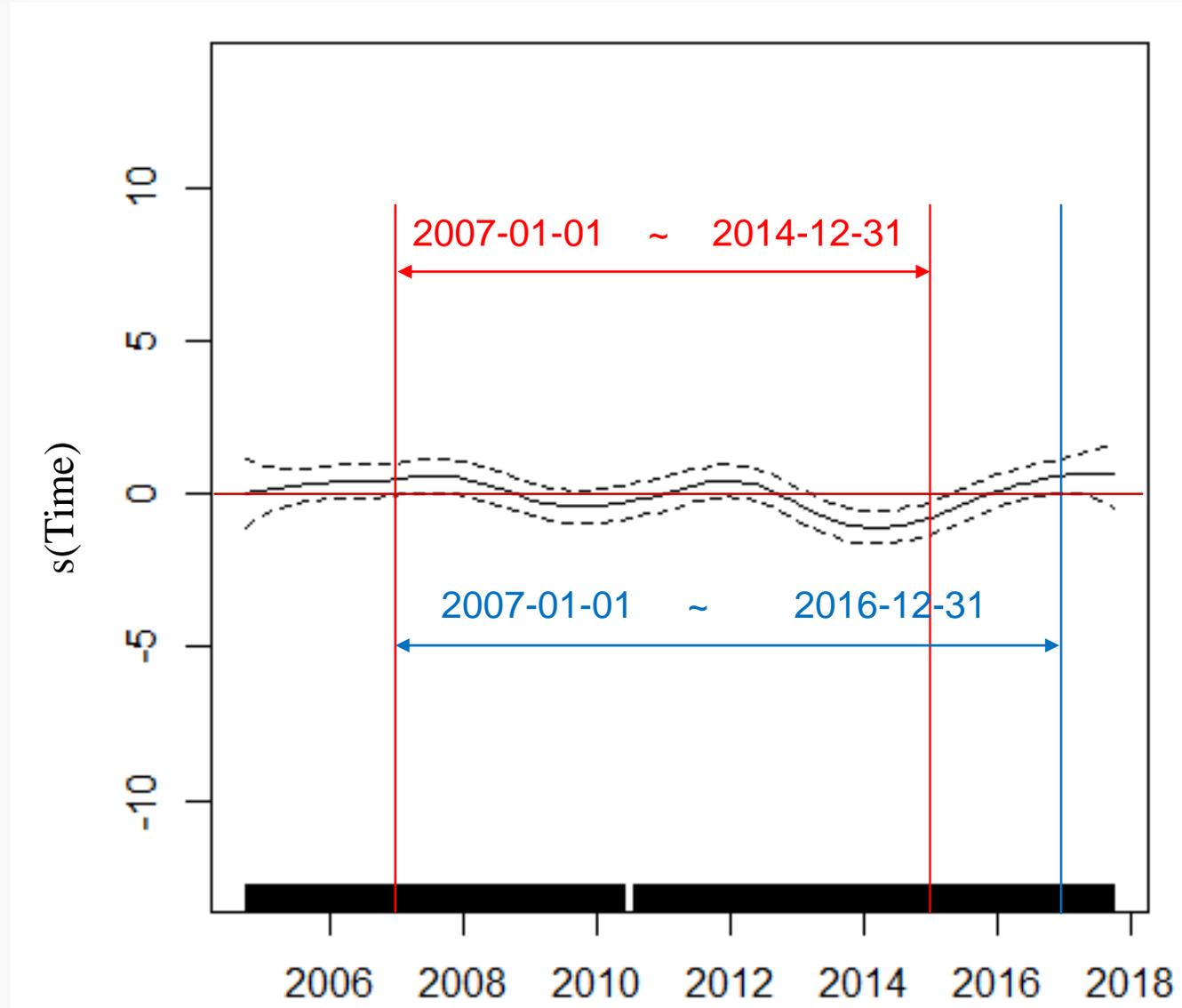
# Water Temperature Trend Estimation

□ Time period: 2007-01-01 ~ 2014-12-31

- Trend over time period:  $-1.27^{\circ}\text{C}$   
95% confidence interval:  $-2.06 \sim -0.48$   
p-value:  $< 0.01$

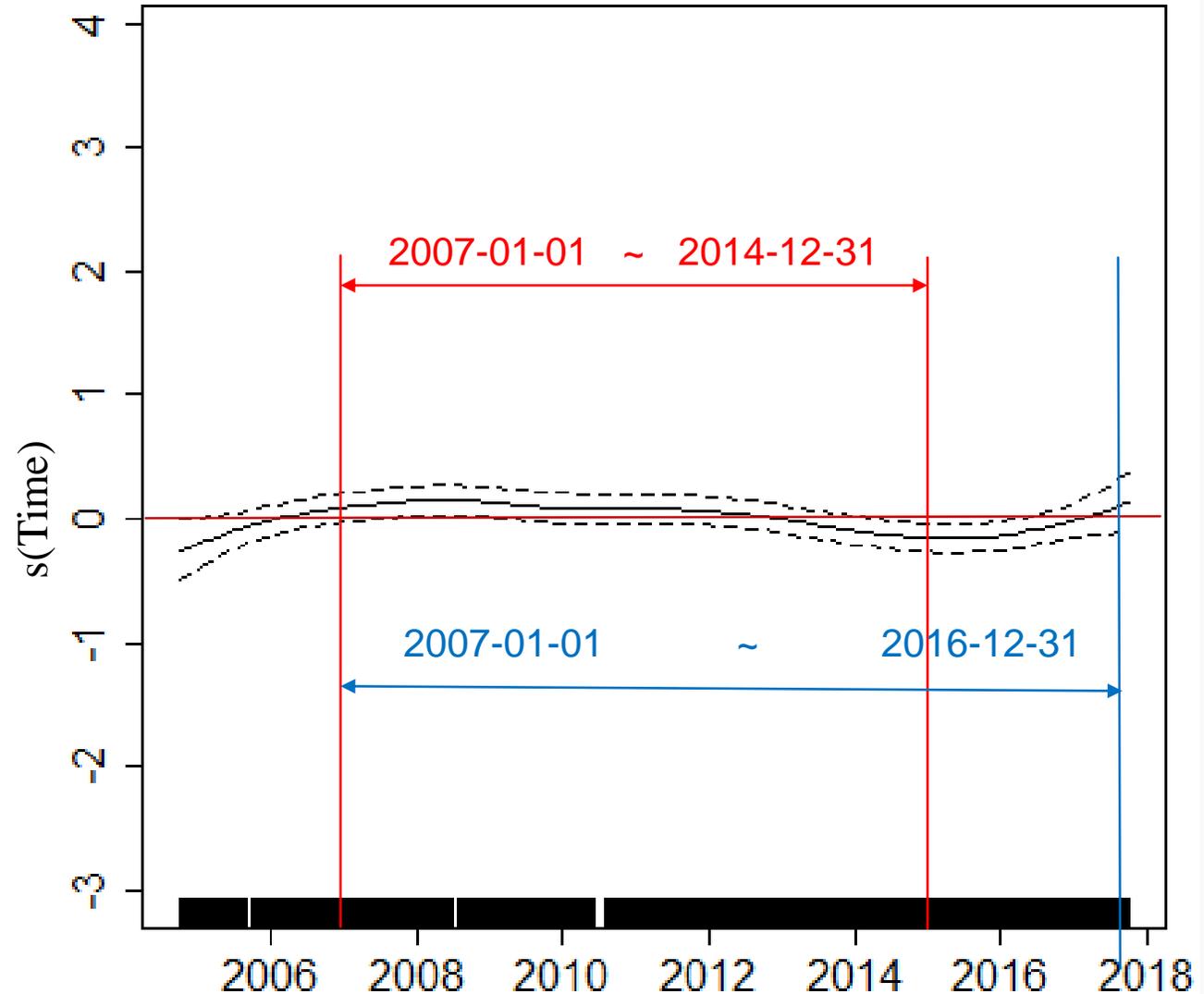
□ Time period: 2007-01-01 ~ 2016-12-31

- Trend over time period:  $0.12^{\circ}\text{C}$   
95% confidence interval:  $-0.7 \sim 0.93$   
p-value: 0.78



# Turbidity Trend Estimation

- ❑ Time period: 2007-01-01 ~ 2014-12-31
  - Trend (log scale): -0.24 FNU ( $p < 0.01$ )  
95% confidence interval: -0.42 ~ -0.06
- ❑ Time period: 2007-01-01 ~ 2016-12-31
  - Trend (log scale): -0.10 FNU ( $p = 0.30$ )  
95% confidence interval: -0.30 ~ 0.09
- ❑ Interpretation of the trend signal between estimation endpoints
  - How can we utilize the variability in the trend time series to better understand/link water-quality responses to episodic changes in the watershed (e.g. stream restoration, floods, or urbanization)?



# GAM Trend Estimation Summary

- ❖ It is flexible to incorporate many possible predictors
- ❖ Decompose the signal into different components over time
- ❖ What does the trend pattern look like over time
- ❖ Test if the trend is significant over a given time period
- ❖ Statistical inference, confidence interval calculation
- ❖ Can short-term trend signals be linked to restoration/disturbance events in the watershed?

Thank you!

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Water-quality monitors  
deployed on the James  
River at Cartersville, VA